R E M A R K S

The above changes in the specification and claims merely place this national phase application in the same condition as it was during Chapter II of the international phase, with the multiple dependencies being removed. Following entry of this amendment by substitution of the pages, only claims 1-6 remain pending in this application.

Attached hereto is a marked-up version of the changes made to the claims by the current amendment. The attached page is captioned "VERSION WITH MARKINGS TO SHOW CHANGES MADE".

Respectfully submitted,

YOUNG & THOMPSON

By Benoît Castel

Benoît Castel
Attorney for Applicants
Customer No. 000466
Registration No. 35,041
745 South 23rd Street
Arlington, VA 22202
Telephone: 703/521-2297

May 3, 2001

VERSION WITH MARKINGS TO SHOW CHANGES MADE

The claims have been amended as follows:

3. (Amended) Arrangement according to claim 1~~ or 2~~, wherein the number of sensors (2(m)) equals the number of actuators (3(n)) and equals the number of controllers (5a(i), 5b(i)), each controller (5a(i), 5b(i)) receiving one of the plurality of sensor signals (p(m)) as input signal and controlling one of the plurality of actuators (3(n)).

4. (Amended) Arrangement to ~~any of the preceding~~ claim~~s~~ **1,** wherein a sound reflective wall (8) is present such that the second surface is between the first surface and the wall (8).

5. (Amended) Arrangement according to ~~any of the preceding~~ claim~~s~~ **1,** wherein one or more detection sensors (7(r)) are arranged for sensing said primary source (4) and providing one or more detection sensor signals (V_{dct}(i)) to said plurality of controllers (5a(i), 5b(i)).

6. (Amended) Arrangement according to ~~any of the preceding~~ claim~~s~~ **1,** wherein a supervising controller (6) is provided to receive signals in dependence on said sensor signals (p(m)) and to monitor long-term behaviour of the arrangement by modifying control parameters of the controllers (5a(i), 5b(i)) in order to ensure overall stability of the arrangement based on a predetermined error criterion as to the sensor signals (p(m)).